

DC-Micromotors

Precious Metal Commutation

0,15 mNm

For combination with
Gearheads:
08/1, 08/2, 08/3
Encoders:
PA2-50, HEM3-256-W

Series 0816 ... S

	0816 N	003 S	006 S	008 S	
1 Nominal voltage	U_N	3	6	8	Volt
2 Terminal resistance	R	11,5	47,0	75,7	Ω
3 Output power	$P_2 \text{ max.}$	0,17	0,16	0,18	W
4 Efficiency	$\eta \text{ max.}$	52	51	50	%
5 No-load speed	n_o	15 700	15 800	16 500	rpm
6 No-load current (with shaft \varnothing 1,0 mm)	I_o	0,016	0,008	0,006	A
7 Stall torque	M_H	0,41	0,40	0,40	mNm
8 Friction torque	M_R	0,04	0,04	0,04	mNm
9 Speed constant	k_n	5 617	2 851	2 329	rpm/V
10 Back-EMF constant	k_E	0,178	0,351	0,429	mV/rpm
11 Torque constant	k_M	1,70	3,35	4,10	mNm/A
12 Current constant	k_I	0,588	0,299	0,244	A/mNm
13 Slope of n-M curve	$\Delta n/\Delta M$	37 999	39 993	43 003	rpm/mNm
14 Rotor inductance	L	47	195	310	μH
15 Mechanical time constant	τ_m	12	13	14	ms
16 Rotor inertia	J	0,03	0,03	0,03	gcm^2
17 Angular acceleration	$\alpha \text{ max.}$	138	132	133	$\cdot 10^3 \text{ rad/s}^2$
18 Thermal resistance	$R_{th 1} / R_{th 2}$	30 / 61			K/W
19 Thermal time constant	τ_{w1} / τ_{w2}	2,9 / 207			s
20 Operating temperature range:					
- motor		- 30 ... + 85			$^{\circ}\text{C}$
- rotor, max. permissible		+ 85			$^{\circ}\text{C}$
21 Shaft bearings		sintered bronze sleeves			
22 Shaft load max.:					
- with shaft diameter		1,0			mm
- radial at 3 000 rpm (1,5 mm from bearing)		0,5			N
- axial at 3 000 rpm		0,1			N
- axial at standstill		20			N
23 Shaft play:					
- radial	\leq	0,03			mm
- axial	\leq	0,2			mm
24 Housing material		steel, nickel plated			
25 Weight		3,5			g
26 Direction of rotation		clockwise, viewed from the front face			
Recommended values - mathematically independent of each other					
27 Speed up to	$n_e \text{ max.}$	13 000	13 000	13 000	rpm
28 Torque up to	$M_e \text{ max.}$	0,15	0,15	0,15	mNm
29 Current up to (thermal limits)	$I_e \text{ max.}$	0,211	0,103	0,085	A

